TRITON

Advanced Deployable Compact Rotorcraft

TEAM MEMBERS:

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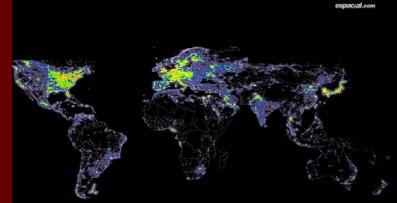
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Introduction



Human population concentrated in coastal regions



SOF missions necessitate submersible deployment



Current deployment method requires ad-hoc land transport

Seek Advanced Deployable Compact Rotorcraft







Mission Profiles

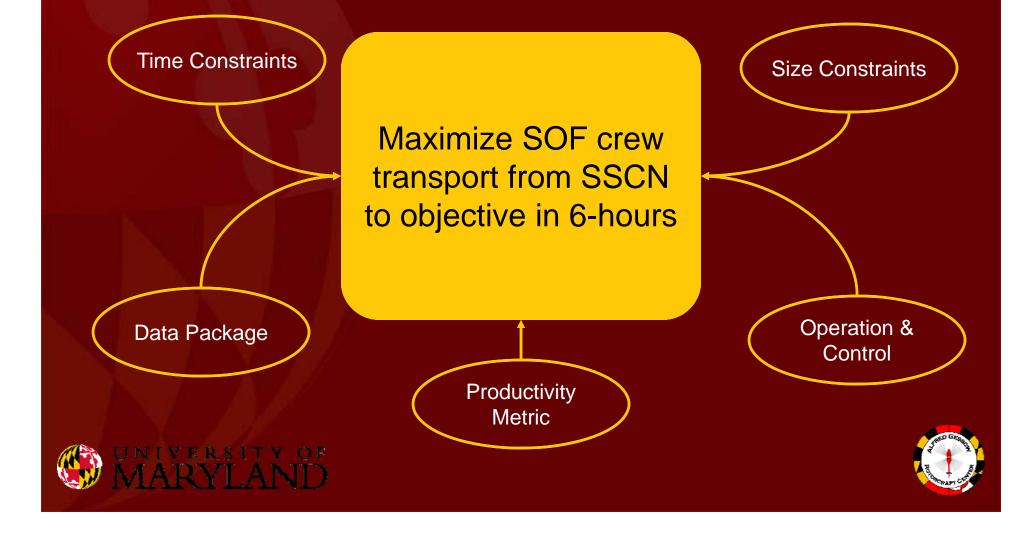
ARV Transport SOF crew Payload: 800 lbs 4-min HOGE drop-off

UEV Unmanned "eye in the sky" Payload: 600 lbs 3-hour loiter





RFP Requirements



Design Methodology

- Design performed in conjunction with ENAE 634 Helicopter Design
- Students developed own analysis tools and software to support component selection and sizing
- All graphics developed using CATIA V5 CAD software and Deep Exploration V5





Launch & Recovery Strategy

Submersible Launch and Recovery Pod (SLRP)

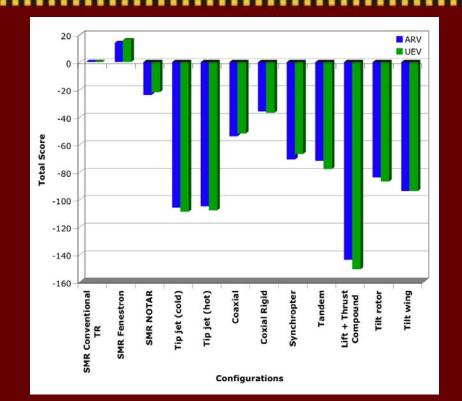
- TRITON ARV/UEV helicopters transported via submersible pod
- ARV crew transported in SLRP with ARV
- Life support provided via umbilical between SSCN and SLRP
- Interior of pod maintained at 1 atm to mitigate decompression sickness
- Submersible pod transforms to floating helicopter pad at surface
- Cable tether provides controlled ascent and descent of SLRP





Configuration Selection

Selection Criteria: •Compact •Cruise-speed •Low noise •Safety •Reliable

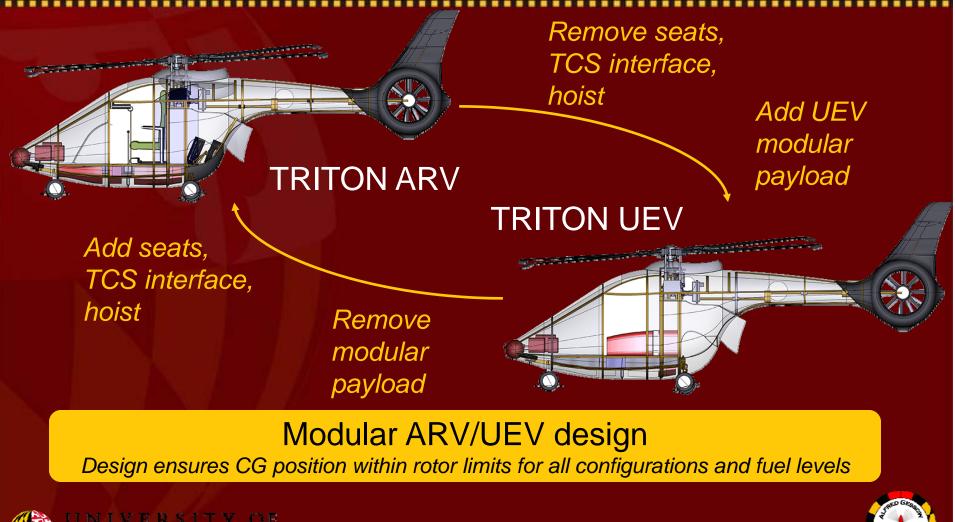


Selected single main-rotor with fan-in-fin as optimal trade between cruise speed, noise and compact design





Modular ARV/UEV Design







Advanced lower fuselage geometry Minimize Earth plowing

CRYSTALOY armored composite skin

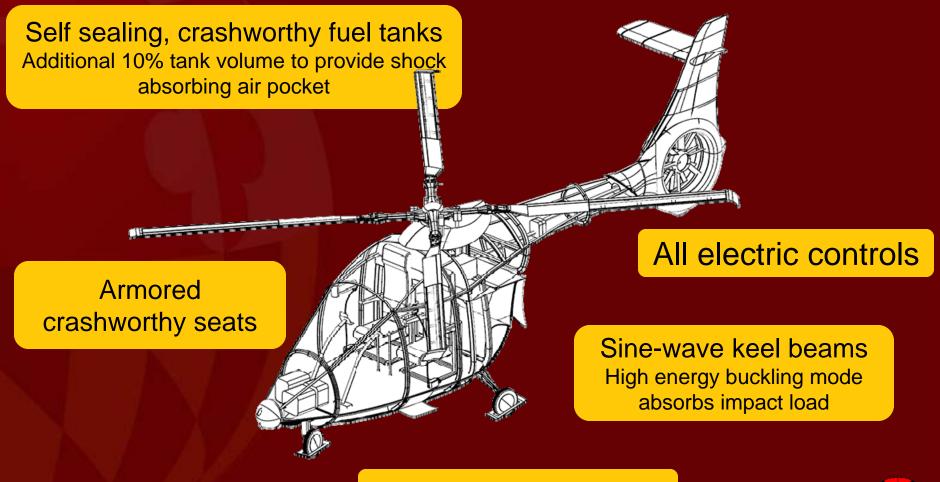
Rear clam-shell doors Fast access to mission equipment

Watertight, corrosion resistant fuselage

Integrated hard points and door step for HOGE crew deployment



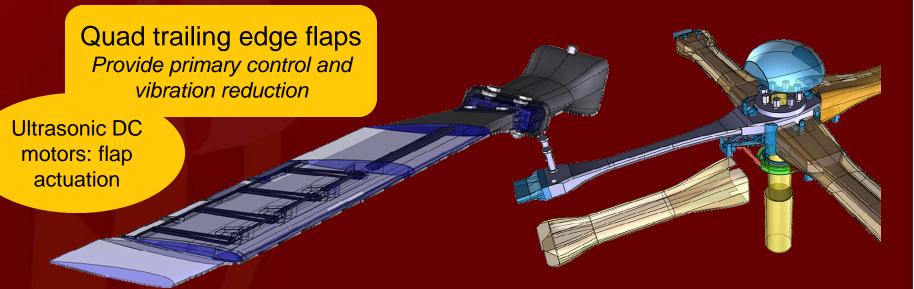
MARYLAND



Retractable landing gear



Swashplateless, bearingless, composite-coupled rotor Reduced weight, drag and maintenance



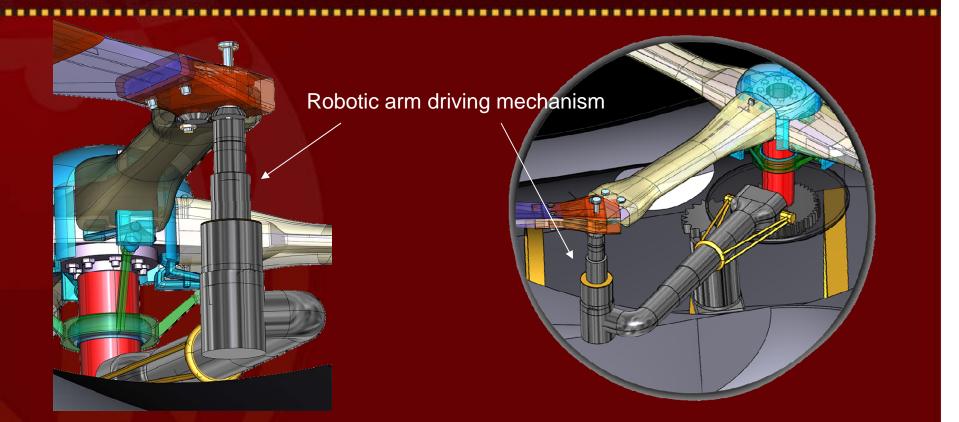
Advanced swept/anhedral tip



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Opposing flexbeams constructed as single body Reduces weight, drag, manufacturing cost and structural complexity





Automatic blade folding with off-blade primary actuation





Folded Dimensions: Length = 19.0 ft Height = 7.5 ft Width = 8.5 ft

Automatic folding tail

Transport 2 TRITONS in a single C130J transport -NO DISSASSEMBLY REQUIRED-







Composite housing Low weight and impervious to sea water

Face-gear input train

Reduced acquisition and maintenance cost through use of common and off-shelf components

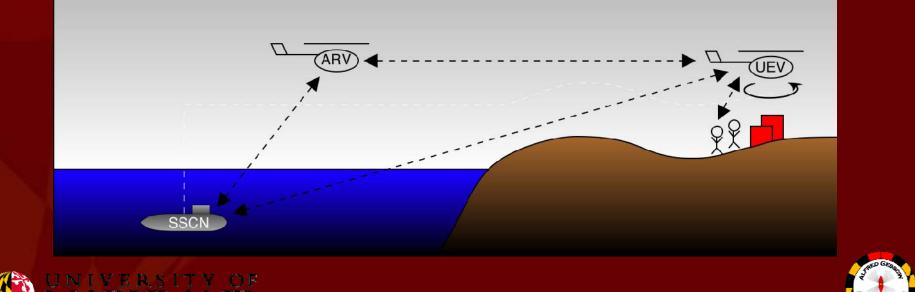
> 5000-hour MTBF for low maintenance





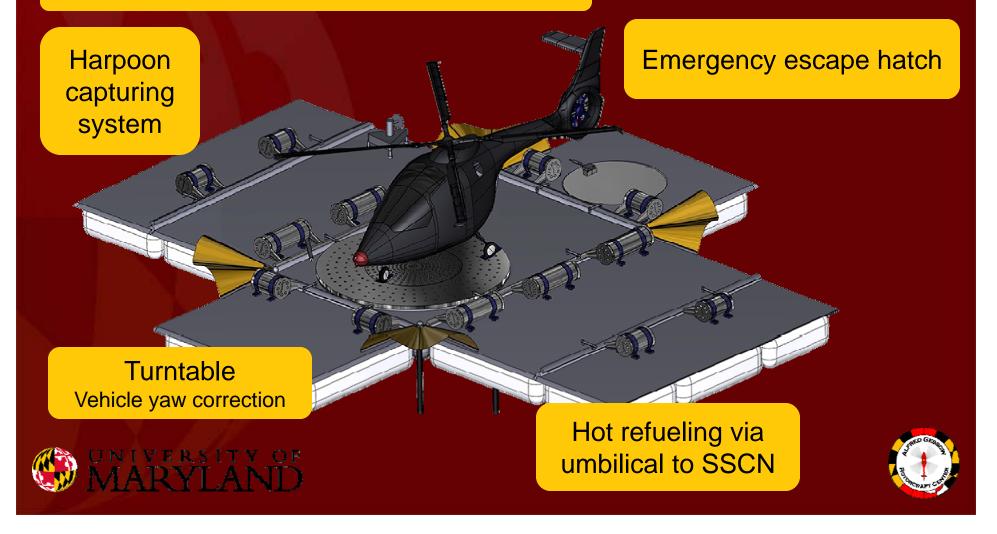
TRITON System Networking

- ARV/UEV operated via Tactical Control System (TCS) software
- TCS provides seamless command and control transfer between operating stations in SSCN, ARV and ground soldier
- Primary data link through TCDL, secondary via UHF/VHF data link
- Portable TCS interface for remote ARV control



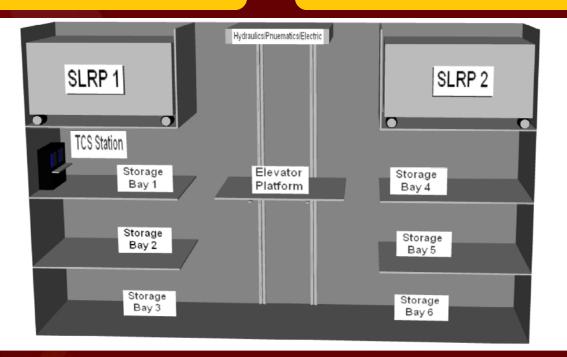
SLRP Design Features

UAV Common Automatic Recovery System



Hangar Configuration

Simultaneous deployment and recovery of 2 TRITON helicopters Central elevator system for optimal use of vertical space

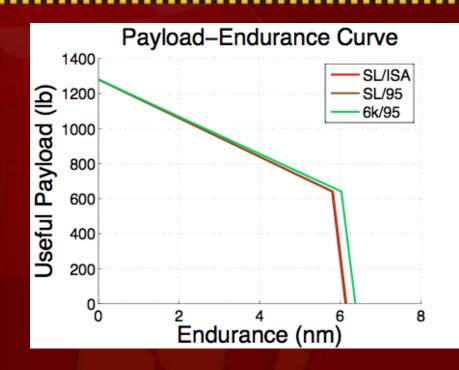


Stow up to 9 TRITON helicopters

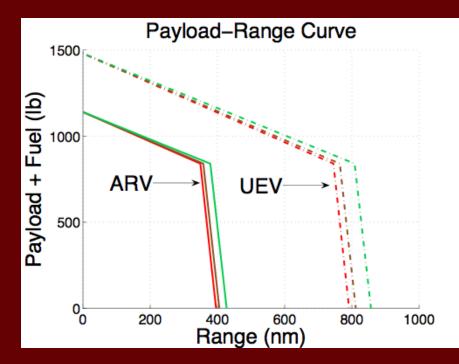




Performance Summary



Best range velocity = 140 kt Hover ceiling (6k/95) > 6000ft





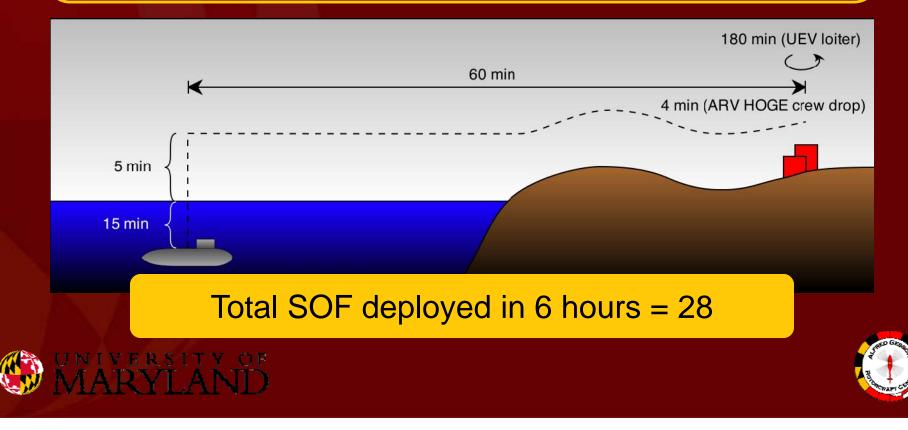


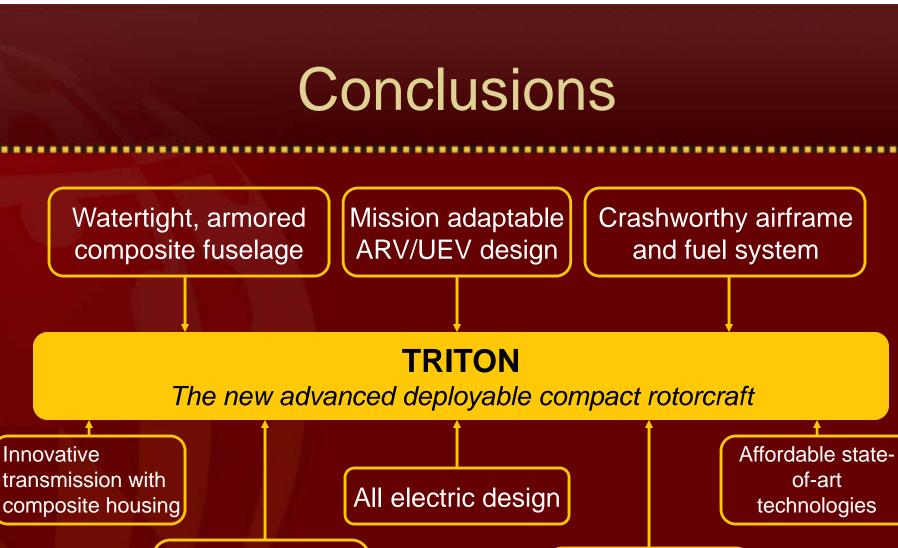
Productivity Metric



2 SLRP 7 TRITON ARV

2 TRITON UEV 2





Swashplateless

multifunctional

control system

Revolutionary automatic blade folding

